

## Technische Universität Berlin



# Optical Remote Sensing

Computer Vision & Remote Sensing

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Duration: 2 hours

Auxiliary Material: No

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### 1 Data Analysis (25P)

You are working with data of a 3-channel multi-spectral scanner with a spatial resolution of 100 m. Your (simplified) image has 8 pixels with the following grey values

Pixel number	Channel 1 (Green)	Channel 2 (red)	Channel 3 (NIR)
1	185	40	200
2	170	20	220
3	40	30	20
4	90	160	110
5	110	150	120
6	180	20	200
7	60	170	100
8	188	40	220

- a) Draw a graph (with all necessary information) showing the feature space of channel 2 and 3 and transfer all the pixels into this feature space. (3p)
- b) With the expert knowledge that there are only **two**(!) different classes in your scene, identify possible cluster centers and mark them **CLEARLY** in the figure of the feature space. **(2p)**

c) Data classification:

- i. Based on your cluster centers, construct (roughly) the decision surface of the minimum distance criterion and add it to your figure. (2p)
- ii. Give a pixel-to-class association. (1p)

d) Classification accuracy:

- i. Is the classification of pixel #3 reasonable (Give a detailed answer)? (2p)
- ii. What do you propose to improve the classification result (or to make it more consistent)? (4p)

- e) *Result interpretation*: Your final goal is to detect vegetated areas. Unfortunately, you do not have any ground truth or reference data.
  - i. Which index can we use to achieve the goal? (Give the full name, not only the acronym). (1p)
  - ii. How is this index calculated? (1p)
    - What is exposed by this index? (2p)
    - Why? (2p)
  - iii. Propose a simple approach to achieve your goal (including some numerical calculation illustrating your proposal). (5p)

#### 2 General Questions (25P)

- a) *Applications of Remote Sensing*: It is your responsibility to develop a sensor that can be used in the following applications:
  - Find a thief which is presumably hiding in a forest difficult to access
  - Detect a bus full of tourists stuck in the Libyan desert with an engine failure. The color of the bus is very similar to the one of the surrounding sand.
  - i. Explain which sensor is well suited for such application. (2p)
  - ii. Why (Give a detailed answer)? (3p)
- b) Sensor design:
  - i. How is an opto-electric scanner constructed (use a sketch)? (2p)
  - ii. How could we acquire the bands of a multi-spectral image simultaneously? (2p)
  - iii. What are the different resolutions that characterize a sensor (give a name and a detailed description for each resolution)? (6p)
- c) Image enhancement.
  - i. Explain the aim of histogram matching. (1p)
  - ii. Describe step-by-step how it works. (3p)
- d) Classification:
  - i. Describe step-by-step how the unsupervised K-Means technique is working. (4p)
  - ii. What do you have to do as a user? (2p)

Altogether **50 points** can be obtained. A short and accurate style should be intended.

#### Pay attention to write a clear and comprehensible text. Always justify your answers!

Lot's of luck and do your best!